

Internal versus External Forces

Internal Forces: Interaction of adjacent particles within a body
 Sum of Internal Forces = 0 (Newton's 3rd Law)

External Forces: Outside of the body

Free-Body Diagrams show only external forces

Static Equilibrium

$$\sum \vec{F} = 0$$

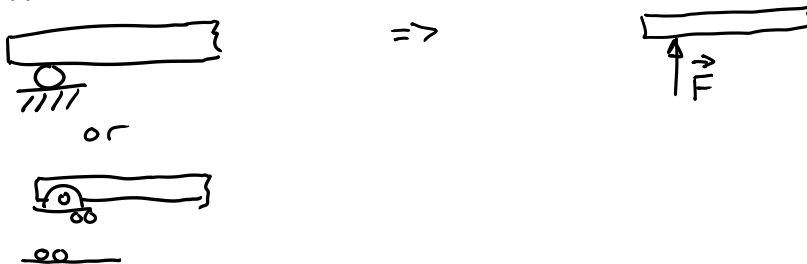
$$\sum \vec{M} = 0$$

Support Reactions in 2-D

- If the support reaction prevents translation, then a force is developed in the opposite direction of the intended translation
- If the support reaction prevents rotation, then a couple moment is developed in the opposite direction of the intended rotation

Examples

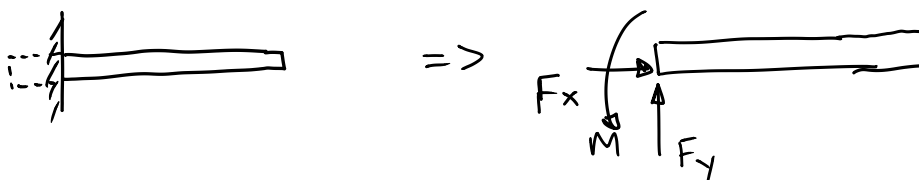
Roller Support



Pinned Support



Fixed Support



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Section 5: Equilibrium of a Rigid Body

Equilibrium

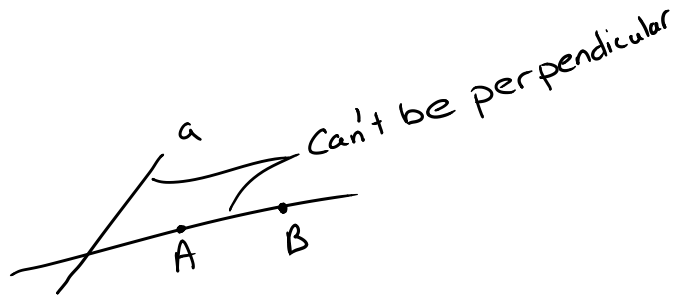
$$\begin{aligned} \sum F_x &= 0 \\ \sum F_y &= 0 \\ \sum M &= 0 \end{aligned}$$

or

$$\begin{aligned} \sum F_a &= 0 \\ \sum M_A &= 0 \\ \sum M_B &= 0 \end{aligned}$$

or

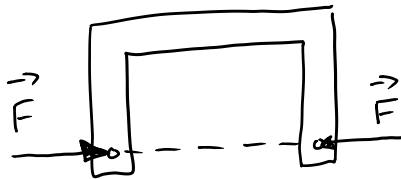
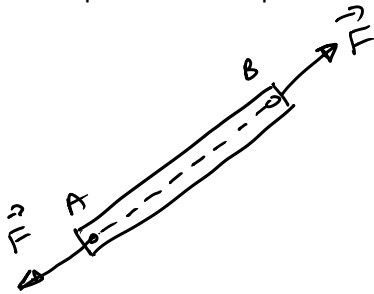
$$\begin{aligned} \sum M_A &= 0 \\ \sum M_B &= 0 \\ \sum M_C &= 0 \end{aligned}$$



A, B, & C can't be on the same line

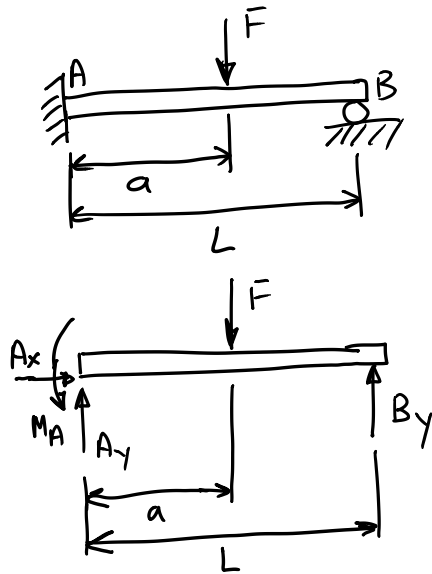
Two-Force Members

- Forces are applied only at two points
- No couple moment is produced



Statically Indeterminate Structures

- More support reactions than equilibrium equations



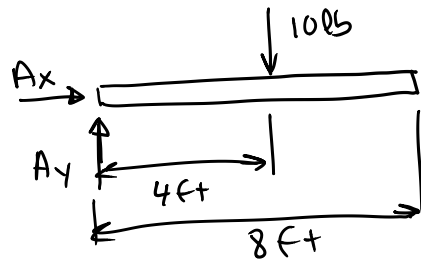
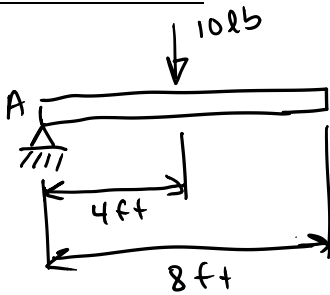
$$\begin{aligned} \rightarrow \sum F_x = 0 &\Rightarrow A_x = 0 \\ +\uparrow \sum F_y = 0 &\Rightarrow A_y + B_y - F = 0 \\ +\curvearrowright \sum M_A = 0 &\Rightarrow M_A - Fa + B_y L = 0 \end{aligned}$$

3 Equations, 4 unknowns \Rightarrow Statically Indeterminate

\Rightarrow Can't be solved using Equilibrium alone

\Rightarrow Must look at deformations

Unstable Structures



$$\begin{aligned} \rightarrow \sum F_x = 0 &\Rightarrow \boxed{A_x = 0} \\ +\uparrow \sum F_y = 0 &\Rightarrow A_y - 10 \text{ lb} = 0 \\ &\quad \boxed{A_y = 10 \text{ lb}} \\ +\curvearrowright \sum M_A = 0 &\Rightarrow -(10 \text{ lb})(4 \text{ ft}) = 0 \\ &\quad \cancel{-40 = 0} \Rightarrow \text{Unstable} \end{aligned}$$

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Support Reactions in 3-D

- Translation in the x, y, and z directions
- Rotation about the x, y, and z axes

$$\begin{array}{ll} \sum F_x = 0 & \sum M_x = 0 \\ \sum F_y = 0 & \sum M_y = 0 \\ \sum F_z = 0 & \sum M_z = 0 \end{array}$$

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Section 5: Equilibrium of a Rigid Body