

Topic

Planar Kinetics: Force and Acceleration

Governing Equations and Assumptions

$$\begin{aligned}
 &\sum F_x = m(a_G)_x \\
 &\sum F_y = m(a_G)_y \\
 &\sum M_P = \sum (M_k)_P \text{ or } \sum M_G = 0
 \end{aligned}
 \left. \vphantom{\begin{aligned} \sum F_x \\ \sum F_y \\ \sum M_P \end{aligned}} \right\} \text{Translation}$$

$$\begin{aligned}
 &\sum F_t = m \alpha r \\
 &\sum F_n = m \omega^2 r \\
 &\sum M_G = I_G \alpha \text{ or } \sum M_O = I_O \alpha
 \end{aligned}
 \left. \vphantom{\begin{aligned} \sum F_t \\ \sum F_n \\ \sum M_G \end{aligned}} \right\} \text{Rotation about a Fixed Axis}$$

$$\begin{aligned}
 &\sum F_x = m(a_G)_x \\
 &\sum F_y = m(a_G)_y \\
 &\sum M_P = \sum (M_k)_P \\
 &a_G = \alpha r \text{ or } F_f = \mu_k N
 \end{aligned}
 \left. \vphantom{\begin{aligned} \sum F_x \\ \sum F_y \\ \sum M_P \\ a_G \end{aligned}} \right\} \text{General Plane Motion}$$

Process

- ① Determine the type motion
- ② Draw Free-Body Diagram and Kinetic Diagram
- ③ Apply the correct Kinetic equations
 \Rightarrow General Plane Motion \Rightarrow Verify rolling versus slipping